

# Assoc. Prof. Dr. Pudit (Sathaporn) LAKSANACHAROEN รศ.ดร. ภูดิส ลักษณะเจริญ Director: Biorobotics Group

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#### WORK EXPERIENCES

2009- present	Adjunct Faculty in the Computer Science & Information Management,
	Asian Institute of Technology (AIT), Thailand
2008	Visiting Research Scientist, National University of Singapore
2008	WiMAX committee, The National Telecommunications Commission (กทช.)
2008	Visiting Jet Propulsion Lab (JPL) NASA, Pasadena, California, USA
2007-2008	Part-time Instructor, Sirindhorn International Institute of Technology, Thailand
2007- present	Researcher หน่วยร่วมวิจัยและพัฒนาหุ่นยนต์เก็บกู้วัตถุระเบิด
	สำนักวิทยาศาสตร์และเทคโนโลยีกลาโหม สำนักงานปลัดกระทรวงกลาโหม
2007- present	Secretary, Thai Robotics Society
	เลขานุการ สมาคมวิชาการหุ่นยนต์ไทย <u>http://www.trs.or.th</u>
2004-2005	Visiting Researcher at Hirose's Robotics Laboratory at
	Tokyo Institute of Technology, O-okayama, Tokyo, JAPAN
	-Design and construction of A New Type Leg-Wheel Hybrid robot for search and
	rescue operations
2002-2006	Research Scientist at The Institute of Field robotics (FIBO),
	มหาวิทยาลัยเทคโนโลยีพระจอมเกล้าธนบุรี (KMUTT), Thailand
	-Conducting research on the humanoid robot arm
2002-2006	Robot contest committee of Thai Robotics Society, Thailand
1996-2001	Research Assistant at Biorobotics Laboratory at CWRU
	-Simulation & Modeling a cricket like robot
	-Study the locomotion of insects to implement movement into the robot
	-Design and control of a microrobot
1998-2000	Assistant Resident Director: Housing & Residence Life at CWRU
	-Provided leadership in the planning & social programs within residence hall
	-Completed administrative task: checking in/out, room inventory.
1993-1995	Maintenance Engineer: Electricity Generating Authority of Thailand
	-Maintained and overhaul stem turbine power plant throughout Thailand
1992-1993	Commissioning Engineer: TPI cement plant, Thailand
	-Inspected and commissioned two new raw material grinding plants

#### **EDUCATION**

Ph.D.	Mechanical Engineering, 2001
	Dissertation: Models and Simulation for design and control of Legged Robots
M.Sc.	Mechanical Engineering, 1998
	Thesis: Symbolic Manipulation of the equation of motion for multi-body systems
	to improve computational efficiency
	Advisor: Roger D. Quinn, Professor of Mechanical and Aerospace Engineering,
	Case Western Reserve University (CWRU), Cleveland, Ohio, USA
B.Eng.	Mechanical Engineering 1992
	King Mongkut's University of Technology Thonburi (KMUTT), Thailand

## **TEACHING EXPERIENCES**

2009-present	Adjunct Faculty in the Computer Science & Information Management
	Asian Institute of Technology (AIT), Thailand
2008-present	Associate Professor
2004-present	Assistant Professor in Department of Mechanical Engineering
	King Mongkut's Institute of Technology North Bangkok (KMITNB)
	Undergraduate courses; Introduction to Robotics, Mechanics of Machinery,
	Engineering Dynamics
	Graduate courses; Engineering Vibrations, Intermediate dynamics
2001-2004	Lecturer in Department of Mechanical Engineering, KMITNB
1998-2001	Mentor Teaching Assistant: Educational Support Services at CWRU
	-Responsible for holding a series of seminars for new TA
	-Emphasize the importance of the instructional role and the value of teaching
1997-1998	Teaching Assistant (TA): Mechanical Engineering Department at CWRU
	-Taught review session once a week for Dynamics and Engineering Vibrations
	-Graded homework

# LEADERSHIP/AWARDS/ACTIVITIES

Advisor of the 1<sup>st</sup> place team winner in the ABU robot contest in Thailand 2006 Final participant of the Thailand Invention Awards 2006 Advisor of the final team in the Thailand Rescue Robot Championship 2005 Graduate Dean's Instructional Excellence Award at CWRU 1998 President of the Organization of Thai Students at CWRU 1996

#### **BOOK PUBLICATION**

Sathaporn Laksanacharoen, "Robotics Engineering", The Technology Promotion Association Thailand-Japan, December, 2005 (in Thai) ISBN: 974-443-151-2

## PUBLICATIONS

Petch Jearanaisilawong, Sathaporn Laksanacharoen, Veeradate Piriyawong and Khatathap Swatdipisal, "Design of A Three-Legged Reconfigurable Spherical Shape Robot", International Conference on Advanced Intelligent Mechatronics (AIM), Singapore, July 14-17, 2009

Petch Jearanaisilawong and Sathaporn Laksanacharoen, "Dynamic Simulation of a Reconfigurable Spherical Robot", 2008 IEEE International Conference on Robotics and Biomimetics (ROBIO) February 21-26, 2009, Thailand

Junya Tanaka, Shuntrou Chigisaki, Shegeo Hirose and Sathaporn Laksanacharoen, "Study of an Amphibious Leg-Wheel Hybrid Mobile Robot "Ferret" (Development of a Butterfly Walking First Prototype)", The Society of Instrument and Control Engineers SI 2007, December 20-22, 2007, Hiroshima, Japan (in Japanese)

Pattaramon Tantichattanont, Szathys Songschon and Sathaporn Laksanacharoen, "Quasi-Static Analysis of a Leg-Wheel Hybrid Vehicle for Enhancing Stair Climbing Ability", 2007 IEEE International Conference Robotics and Biomimetics (ROBIO), Yaong Bay, Sanya, China , December 15-18, 2007

Kritsana Sripanomwan, Benchaporn Limtammakorn and Sathaporn Laksanacharoen, "Control of a Four-Legged Robot Model Using a Back-Propogation Neural Networks", The 20th Conference of Mechanical Engineering Network of Thailand (MENETT), Nakornratchasrima, Thailand, October19-21, 2005 (in Thai)

Sathys Songschon and Sathaporn Laksanacharoen, "Rubber muscle for humanoid arm", The 19th Conference of Mechanical Engineering Network of Thailand, Phuket, Thailand, October 19-21, 2005 (in Thai)

Saksiri Sirisampan and Sathaporn Laksanacharoen, "Human arm motion analysis using image processing under linux", The 19th Conference of Mechanical Engineering Network of Thailand, Phuket, Thailand, October 19-21, 2005 (in Thai)

Sunton Wongsiri and Sathaporn Laksanacharoen, "Design of An Intelligent Prosthetic Arm", International Symposium on Biomedical Engineering 2004 (ISBME2004), Bangkok, Thailand, November 16-18, 2004

Kawee Suwannasit and Sathaporn Laksanacharoen, "A Bio-Inspired Hybrid Leg-Wheel Robot", IEEE Tencon2004, Chiangmai, Thailand, November 21-24, 2004

Kawee Suwannasit and Sathaporn Laksanacharoen, "A Hybrid Leg-Wheel Robot", The 18th Conference of Mechanical Engineering Network of Thailand, KhonKan, Thailand, October 18-20, 2004 (in Thai)

Sathaporn Laksanacharoen, "Artificial Muscle Construction Using Natural Rubber Latex in Thailand", The 3rd Thailand and Material Science and Technology Conference, Miracle Grand Hotel, Bangkok, Thailand, August 10-11, 2004

S. Wongsiri and S. Laksanacharoen, "Design and Construction of An Artificial Limb Driven by Artificial Muscles for Amputees", PSU-UNS International Conference 2003: Energy and the Environment, Prince of Songkla University, Hat Yai, Songkla, Thailand, December 11-12, 2003

S. Laksanacharoen and S. Wongsiri, "Design of Apparatus to Study Human Elbow Joint Motion", The IEEE EMBS Asian-Pacific Conference on Biomedical Engineering 2003, Kyoto-Osaka-Nara, Japan, October 20-22, 2003

S. Laksanacharoen and S. Wongsiri, "Design and Construction of Rubber Pneumatic Artificial Muscles", The 17th Conference of Mechanical Engineering Network of Thailand, Prachinburi, October 15-17, 2003

S. Wongsiri and S. Laksanacharoen, "The Design of Medical Equipments through Computer Modeling", 19th Annual Academic Meeting, Faculty of Medicine, Prince of Songkla University, Vol. 21, August 13-15, 2003

S. Laksanacharoen, R.D. Quinn, and R.E. Ritzmann, "Modeling of Insect's Legs by Inverse Kinematics Analysis", International Symposium on Adaptive Motion of Animals and Machines, Kyoto, Japan, March 4-8, 2003

Birch, M.C.; Quinn, R.D.; Hahm, G.; Phillips, S.M.; Drennan, B.T.; Fife, A.J.; Beer, R.D.; Xinyu Yu; Garverick, S.L.; Laksanacharoen, S.; Pollack, A.J.; Ritzmann, R.E." Cricket-based robots"; Robotics & Automation Magazine, IEEE Volume 9, Issue 4, Dec. 2002 Page(s):20 – 30

A. Fife, S. Laksanacharoen, R. D. Quinn, R. D. Beer, and R. E. Ritzmann "The Evolution of Neural Network Controllers for the Targeted Swing of Cockroach-like Robot ", IEEE 2002 World Congress on Computational Intelligence, Hawaii, USA, May 12-17, 2002

S. Laksanacharoen, A.J. Pollack, G.M. Nelson, R.D. Quinn and R. E. Ritzmann "Biomechanics and Simulations of Cricket for Microrobot Design ", IEEE International Conference on Robotics and Automation, San Francisco, USA, April 24-28, 2000

M.C. Birch, S. Laksanacharoen, R.D. Quinn, A.J. Pollack, and R.E. Ritzmann. " Development of a Microrobot based on Cricket Biomechanics ", Society for Neuroscience Abstracts Vol 25 Part 1, 29th Annual Meeting, Miami Beach, FLorida, USA. October 23-28, 1999